### CROUZET - BLDC PLANETARY GEARED MOTOR WITH INTEGRATED TNI21 DRIVE

801495XX TNI21 Planetary 52mm gearmotor 77W 12→32Vdc 13→593rpm 25Nm max

- 12→32 V dc, 52→81 mmØ, 25→120 Nm, 11→775 rpm
- Speed & torque control. Easy use
- Reduce control panel space & cabling
- Long life (>20,000 hours)
- IP65 as standard



CROUZET

#### PRODUCT DESCRIPTION

The TNi21 integrated drive is ideal for applications where speed and torque control is required.

The long lifetime of the brushless motor (>20,000 hours with rated load) means it is ideal for continuous or long duty applications.

Having the drive integrated into the motor can also save control panel space, reduce cabling and save set-up time.

3 motor sizes available with the same diameter (57mm x 57mm), with increasing motor lengths for more power/torque.

Planetary & worm gearbox options available for reducing the speed & increasing the output torque.

Pre-set I/O mean that the motor can be used immediately without any complex preliminary set-up. It can be controlled via basic switches or by external PLC. Motor power and logic connections are via cable output or connector options.

The motors are rated to IP65 dust/water protection class as standard.

Options for adapation to the standard motor include adding an encoder, holding brake, special output shaft, special connectors, upgraded IP protection & special firmware developed according to your specific application requirements.

\* Product datasheets & 3D drawing for 0-10Vdc, cable version attached as an example. Further information for PWM version, brake options & connector version available upon request.

Full documentation & user manuals also available upon request.

# **TECHNICAL DATA**

| Diameter   | 52 mm     |
|--|-----------|
| Integrated control                                   | TNi21     |
| IP class   | IP65      |
| Life span  | 20,000h   |
| Max. torque  | 25 Nm     |
|  |           |
| Number of pulses per revolution                      | 12        |
| Number of pulses per revolution Positioning feedback | 12<br>Yes |
|  |           |
| Positioning feedback                                 | Yes       |
| Positioning feedback                                 | Yes       |

13rpm→593rpm

GEARBOXES FOR DCmind BRUSHLESS RANGE

Supply voltage

Type of gearbox

12 V DC, 24 V DC

Planetary  $1 \rightarrow 3$  stages

80140: 123 max. Parallel kmy 4 x 4 x 16 DIN 6885 A M4 x 10 4 x M5 at 90°, depth 10 over O 40

L1 1 stage: 55.3 ±0.5 L1 2 stages: 69.5 ±0.5 L1 3 stages: 83.7 ±0.5

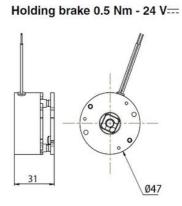




| A article at  | Planetary (0.62           |      |                  | Planetary () (c) |          |                          | Planetary 0 81             |      |                   | Worm                       |
|---|---------------------------|------|------------------|------------------|----------|--------------------------|----------------------------|------|-------------------|----------------------------|
| (54)  | 810495                    |      |                  | 810490           |          |                          | #10492                     |      |                   | 810410                     |
|   | Providence and the second |      |                  |                  |          |                          | 125,879                    |      | D-110             |                            |
| 0140 TN21   | potess Thigh              |      |                  | BOTHIN TNOT      |          |                          |                            |      | BO1410 TN/21      |                            |
| CSAC THURS  | -                         |      |                  | 801896 TN21      |          |                          | 401497                     | TNOT | epteto TNI25      |                            |
| 1NO THERE   |                           |      |                  |                  |          |                          | BOORNY THICH               |      |                   | #02810 Thi21               |
| 2140.05521  | 001416 SMQ1               |      |                  | 801490 SM621     |          |                          |                            |      |                   | 801410 SMQ1<br>801810 SMQ1 |
| 2180 SM(21  |                           |      |                  | 801896 SM21      |          |                          | 801897 SM21<br>802997 SM21 |      |                   |                            |
| 1260 SM21<br>earbox characteristics   | _                         |      |                  | -                |          | _                        | 102697                     | 5MQ1 | _                 | 802810 SM21                |
| earbox characteristics  | -                         |      |                  | -                |          |                          | Anna Para                  |      |                   |                            |
| avimum permitted torque (Nin)   | 4                         | 12   | 25               | 8                | 25       | 50                       | 20                         | 60   | 120               | 10                         |
| ficency   | 0.8                       | 0.75 | 0.7              | 0.9              | 0.8      | 0.7                      | 0.9                        | 0.8  | 0.7               | 0.6-0.3                    |
| Mail: dynamic list (dall)   | 4                         | 10   | 15               | 7                | 30       | 35                       |                            | 12   | 20                | 10                         |
| Mail dynamic load IdaN  | 20                        | 32   | 45               | 24               | 36       | 52                       | 40                         | 60   | 100               | 15                         |
| senting temperature   | -20 -= = 70*0             |      | -20              |                  |          | -20 70 -C                |                            |      | -20 +4 +70°C      |                            |
| neget (ng)  | 0.7                       | 0.8  | 1.1              | 0.8              | 1.2      | .1.0                     | 5.8                        | 2.5  | 3.2               | 0.7                        |
| tandard reduction ratios  | 6.75                      | 25   | 90<br>169<br>308 | 6.76             | 19 22 44 | 100<br>139<br>236<br>308 | 6                          | 19   | 100<br>139<br>236 | 5 - 10 - 20 - 30 - 50      |
| ther ratios possible  |                           |      | _                |                  |          |                          |                            |      | _                 | 15 - 100                   |
| or manufacture of the second se |                           |      |                  |                  |          |                          |                            |      |                   |                            |

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# Options



|                              | Connector<br>M16 | Cable color             |
|------------------------------|------------------|-------------------------|
| Power ground                 | G+M              | AWG16 Blue              |
| Power supply +12 to +32 V DC | E+E              | AWG16 Brown             |
| Logic ground                 | 14               | AWG24 Black (5)         |
| Input 1 On/Off               | C                | AWC24 Green (1) 4-1 Amm |
| Input 2: Direction           | 8                | AllVQ24 Yellow (2)      |
| Input 3 Speed                | 1                | AWQ24 Orange (4)        |
| Output 1 Tachometer*         | A                | All G24 Brown (6) +     |
| Output 2: Real direction     | L                | AWG24 Red (8)           |
| Input 4: Torque              | D                | AWCOLE (Bue (3)         |
| Output 3: Torque at max.     | K                | AWG24 Purple (7)        |